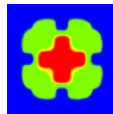


# Approximation of Eigenvalue Problems II

## Solving the discrete eigenvalue problem

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- 1 **Vector iterations**
- 2 **Krylov space methods**
- 3 **The Jacobi-Davidson Method**

- Z. Bai, J. Demmel, J. Dongarra, A. Ruhe, H. van der Vorst, eds. *Templates for the Solution of Algebraic Eigenvalue Problems: A Practical Guide*. SIAM. 2000
- Y. Saad. *Numerical Methods for Large Eigenvalue Problems*. SIAM. 2011

- 1 Vector iterations**
  - Single vector iterations
  - Simultaneous vector iterations

- 2 Krylov space methods**

- 3 The Jacobi-Davidson Method**

## The standard EVP

$$Au = \lambda u$$

- Eigenvalues:  $\lambda_k$
- Eigenvectors:  $u_k$
- Eigenspaces  $U_k$

## The generalized EVP

$$Au = \lambda Mu$$

- Generally,  $A, M \in \mathbb{C}^{n \times n}$
- Variational EVP always lead to the second form
  - $M$  symmetric (Hermitian), positive definite
  - semi-definite possible

# Properties of A

- Hermitian (symmetric)
  - $\mathbb{C}^n = \text{span}(u_1, \dots, u_n)$
  - $(u_i, u_j) = \delta_{ij}$
  - $\lambda_k$  real
- normal
  - $\mathbb{C}^n = \text{span}(u_1, \dots, u_n)$
  - $(u_i, u_j) = \delta_{ij}$
  - $\lambda_k$  complex
- diagonalizable
  - $\mathbb{C}^n = \text{span}(u_1, \dots, u_n)$
  - $\lambda_k$  complex
- other
  - less than  $n$  eigenvectors
  - $\mathbb{C}^n \neq \text{span}(u_1, \dots, u_n)$

} good  
} bad  
} ugly

# Restriction to real, symmetric matrices

- Real eigenvalues and eigenvectors
- Orthogonality: for any  $\overset{V}{\cancel{u}} \in \mathbb{R}^n$  holds

*Parseval*

$$v = \sum_{k=1}^n \alpha_k u_k, \quad \|\overset{V}{\cancel{u}}\|^2 = \sum_{k=1}^n \alpha_k^2$$

- Even if we do not know the eigenvectors in advance, knowing their existence helps

## Power iteration (von Mises)

Initial vector  $v$

**for**  $i := 1, \dots$  **do**

$v := Av$

**end for**

$\lambda := \frac{a(v,v)}{(v,v)}$

# Normalization

- Vectors may grow or shrink beyond numerical range
- Normalization in every step or every few steps

## Power iteration (von Mises)

```
Initial vector  $v$   
for  $i := 1, \dots$  do  
     $v := Av$   
     $v /= \|v\|$   
end for  
 $\lambda := a(v, v)$ 
```

## Power iteration with stopping criterion

Initial vector  $v$  with  $\|v\| = 1$

**repeat**

$$w := Av$$

$$\theta := (w, v)$$

$$r = w - \theta v$$

$$v = \frac{1}{\|w\|} w$$

**until**  $\|r\| \leq \varepsilon$

$$\lambda := \theta$$

$$u := v$$

# Convergence estimate

- Use the fact that  $A$  is orthogonally diagonalizable

$$v = \sum_{k=1}^n \alpha_k u_k \quad Av = \lambda_n \left( \alpha_n u_n + \sum_{k=1}^{n-1} \frac{\lambda_k}{\lambda_n} \alpha_k u_k \right)$$

- Renormalize for simplicity  $\alpha_n = 1$

- Result of step  $j$

$$v^{(j)} = u_n + \mathcal{O} \left( \left( \frac{\lambda_{n-1}}{\lambda_n} \right)^j \right)$$

$$\theta^{(j)} = \lambda_n \left( 1 + \mathcal{O} \left( \left( \frac{\lambda_{n-1}}{\lambda_n} \right)^{2j+1} \right) \right)$$

- Residual

$$w^{(j)} - \theta^{(j)} v^{(j)} = \lambda_n \mathcal{O} \left( \left( \frac{\lambda_{n-1}}{\lambda_n} \right)^{j+1} \right)$$

*$\alpha_n = 0$  caused by floating point arithmetic*

*$|\lambda_n| \neq |\lambda_{n-1}|$*

- Power iteration can only approximate the largest eigenvalue

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- Smallest eigenvalue: apply iteration to  $A^{-1}$

# Spectral transformations

- Power iteration can only approximate the largest eigenvalue
- Smallest eigenvalue: apply iteration to  $A^{-1}$
- Convergence speed depends on ratio of the two largest eigenvalues
- Shift and invert: choose  $\sigma$  close to the desired eigenvalue  $\lambda_*$  and apply iteration to

$$(A - \sigma I)^{-1} \quad \mu_* = \frac{1}{\lambda_* - \sigma} \ll \frac{1}{\lambda_k - \sigma} = \mu_k$$

## Inverse iteration (Wieland)

Initial vector  $v$  with  $\|v\| = 1$

**repeat**

Solve:  $(A - \sigma I)w := v$

$\theta := (w, v)$

$r = w - \theta v$

$v := \frac{1}{\|w\|} w$

**until**  $\|r\| \leq \varepsilon$

$\lambda := \sigma + \frac{1}{\theta}$

$u := v$

Adapt shift in every step

## Rayleigh quotient iteration

Initial vector  $v$  with  $\|v\| = 1$

Initial shift  $\sigma$

**repeat**

Solve:  $(A - \sigma I)w := v$

**if singular then stop**

$\theta := \|w\|$

$\sigma \leftarrow \sigma + \frac{(w, v)}{\theta^2}$

$v := \frac{1}{\theta} w$

**until**  $\theta \geq \varepsilon^{-1/2}$

$\lambda := \sigma$

$u := v$

Eigenvalues converge third order!

# How to compute the second eigenvalue?

# How to compute the second eigenvalue?

- Iterate two vectors at a time:  $V = (v_1, v_2) \in \mathbb{R}^{n \times 2}$

$$\tilde{V} = (Av_1, Av_2) \in \mathbb{R}^{n \times 2} \quad \tilde{V} = AV$$

# How to compute the second eigenvalue?

- Iterate two vectors at a time:  $V = (v_1, v_2) \in \mathbb{R}^{n \times 2}$

$$\tilde{V} = AV$$

- Orthogonalize and normalize (Gram-Schmidt)

$$v_1 = \frac{1}{\|w_1\|} w_1$$

$$w_1 = \tilde{v}_1$$

$$v_2 = \frac{1}{\|w_2\|} w_2$$

$$w_2 = \tilde{v}_2 - (\tilde{v}_2, v_1) v_1$$

# Gram-Schmidt revisited

- Simultaneous iteration of  $k$  vectors

$$\begin{aligned}\gamma_1 v_1 &= \tilde{v}_1 \\ \gamma_2 v_2 + \beta_{21} v_1 &= \tilde{v}_2 \\ \vdots &\vdots \\ \gamma_k v_k + \beta_{k1} v_1 + \cdots + \beta_{k,k-1} v_{k-1} &= \tilde{v}_k\end{aligned}$$

- Matrix form

$$VR = \tilde{V}, \quad R = \begin{pmatrix} \gamma_1 & \beta_{21} & \cdots & \beta_{k1} \\ & \gamma_2 & \cdots & \beta_{k2} \\ & & \ddots & \\ & & & \gamma_k \end{pmatrix}$$

## Simultaneous vector iteration (truncated QR method)

Initial matrix  $V \in \mathbb{R}^{n \times k}$  with orthogonal columns

**while** true **do**

$W := AV$

$H := V^T W$

**if**  $\|W - VH\| \leq \varepsilon$  **then stop**

    QR-factorize:  $VR = W$

**end while**

$\lambda_i = h_{ii}$

$u_i = V_{:,i}$  or QR-factorize  $VR = W$

- Can be applied with shift and invert
- Orthogonalization can be done every  $m$  steps

- Assumption: Some eigenvalues are less important
- Replace the product  $A^m V$  by the polynomial  $p_m(A)$
- Choose  $p_m$  such that it is
  - small where eigenvalues are not important
  - large where they are important
- Example: Chebyshev polynomials to suppress eigenvalues in  $[\sigma - \rho, \sigma + \rho]$ :

$$T_m \left( \frac{A - \sigma I}{\rho} \right)$$

# Implicit shift

- In each step, QR-factorize  $A - \sigma I$
- If  $\sigma = \lambda$ , then

$$RQ = \begin{pmatrix} \ddots & & & \\ & \ddots & & \\ & & \ddots & \\ 0 & \dots & 0 & \lambda \end{pmatrix}$$

- The eigenvector gets reproduced exactly
- Find shifts close to  $\lambda_k$  to accelerate convergence

# Remarks on the generalized EVP

$$Au = \lambda Mu$$

- Apply the vector iterations to

$$C = M^{-1}A$$

- Not symmetric
- Cholesky decomposition  $M = LL^T$  if  $M$  is s.p.d.

$$C = L^{-1}AL^{-T} \quad M^{-1} = L^{-T}L^{-1}$$

- Symmetric
- Stability if  $M$  is ill-conditioned?

Inverse iterations can be rewritten by changing inner product

### Example: Inverse iteration for generalized EVP

Initial vector  $v$  with  $\|v\|_M = 1$

**repeat**

Solve:  $(A - \sigma M)w := Mv$

$\theta := (w, v)_M$

$r = w - \theta v$

$v := \frac{1}{\|w\|} w$

**until**  $\|r\| \leq \varepsilon$

$\lambda := \sigma + \frac{1}{\theta}$

$u := v$

# Why are we solving generalized EVP?

- We have to distinguish between the eigenvalues of the operator

$$A : H \rightarrow H^*$$

$$a(u, v) = \lambda(u, v)$$

and the matrix  $A$  which is generated by applying the bilinear form to the basis functions

$$Ax = \lambda x$$

- The second depend on the basis, the first do not
- The first make sense in  $H$ , the second only discretely
- The Ritz isomorphism is missing in the second EVP

# Matrix structures (FEM)

- Basis typically large,  $n \approx 10^7$
- Applying matrix is cheap  $O_m = n \ll n^2$

## Optimal complexity

A single step of an iterative method is of optimal complexity, if its operation count is of the same order as  $O_m$ .

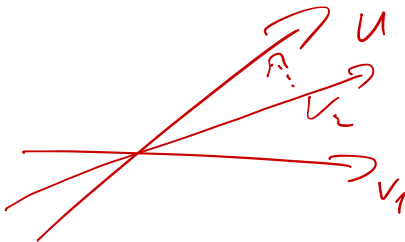
- Power iteration is of optimal complexity
- Inverse iteration is of optimal complexity if the linear solver is
- The truncated QR method is of optimal complexity
- The full QR method is not

## 1 Vector iterations

## 2 Krylov space methods

- Basic idea
- The Lanczos method
- Implicitly restarted Lanczos

## 3 The Jacobi-Davidson Method



- Krylov space methods are projection methods
  - Approximate large EVP by exact solution to small EVP
  - Approximation space growing in each step
  - Ritz-Galerkin method

## Krylov space

$$\mathcal{K}_m(A, v) = \text{span} \left( v, Av, \dots, A^{m-1}v \right)$$

- Krylov spaces are generated by subsequent powers of  $A$
- The vectors  $A^j v$  become more and more parallel as  $j$  increases
- Methods must maintain an orthogonal basis for stability

- $V_m$  is orthonormal basis of  $\mathcal{K}_m(A, v)$
- The projected matrix

$$T_m = V_m^T A V_m$$

- $(\theta_k, s_k)$  eigenpairs of  $T_m$
- Ritz vectors

$$u_k^{(m)} = V_m^T s_k$$

# The Lanczos method

Initial vector  $r$

**for**  $j = 1, 2, \dots$  **do**

$$\beta_{j-1} = \|r\|_M$$

$$v_j = \frac{1}{\beta_{j-1}} r$$

$$r = Av_j \text{ or solve } (A - \sigma M)r = v_j$$

$$r \leftarrow \beta_{j-1} v_{j-1}$$

$$\alpha_j = (v_j, r)_M$$

$$r \leftarrow \alpha_j v_j$$

} Gram-Schmidt

$$r \perp v_{j-1}$$
$$r \perp v_j$$

Optional reorthogonalization

Compute  $T_j$  and diagonalize  $T_j = S\Theta^{(j)}S^T$

**if** converged **then stop**

**end for**

- Variant with shift and invert
- Variant for generalized EVP
  - $r$  is  $M$ -orthogonal to  $V_j$

# The projected system

$$T_m = \begin{pmatrix} \alpha_1 & \beta_1 & & & \\ \beta_1 & \alpha_2 & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \ddots & \beta_{m-1} \\ & & & \beta_{m-1} & \alpha_m \end{pmatrix}$$

- Tridiagonal, symmetric
- QR factorization particularly simple
- Recursive construction

$$AV_j = V_j T_j + r_j e_j^T, \quad V_j^T r_j = 0$$

- Approximation of Ritz pair  $(\theta_k, v_k^{(m)} = V_m s_k)$

$$r_k^{(m)} = Av_k^{(m)} - \theta_k v_k^{(m)} = (AV_m - V_m T_m) s_k = v_{m+1} \beta_m s_{m,k}$$

- Estimate

$$\|r_k^{(m)}\| = |\beta_m s_{m,k}|$$

# Reorthogonalization

- Not necessary for conjugate gradient method
  - Only last approximation counts
- Recursive orthogonality suffers as soon as an eigenvalue is well approximated
  - roundoff errors dominate
- Reorthogonalization of the whole basis  $V_m$  necessary

?

# Multiple eigenvalues

- The Lanczos method works with multiple eigenvalues
  - Only one eigenvector in the eigenspace
  - Depending on initial vector
- Locking of eigenvectors
  - Flag eigenpairs as converged if residual is small
  - Do not iterate those anymore
  - Keep vectors in orthogonalization
  - Roundoff errors force additional eigenvectors

# Restarting

- The Lanczos basis may become very large before convergence
  - Reorthogonalization costly
- Solution: cutting off the basis (restart)
- Explicit restart
  - Delete basis after  $m$  steps
  - Begin with last iterate
- Implicit restart
  - Keep part of the basis and fill up again

$v_1$   ~~$v_2$~~   ~~$v_3$~~   ~~$v_4$~~   $v_{k+1}$  ...  ~~$v_n$~~

- Split Krylov space of size  $m = k + p$  into
  - $k$  desired Ritz vectors
  - $p$  undesired Ritz vectors
- Selection criterion by selecting from  $\theta_1, \dots, \theta_m$ 
  - the largest Ritz values
  - other choices

# Implementation of implicit restart

- 1 Compute until Krylov space has dimension  $m = k + p$
- 2 Apply implicitly shifted QR with the  $p$  undesired Ritz values
  - Eigenvalues of  $T_m$  with these eigenvalues will be in the end
  - First  $k$  vectors will be more desirable Ritz vectors

$$T_m = \left( \begin{array}{c|c} Q_k & x \\ \hline x & x \end{array} \right) \rightarrow T_k = Q_k$$

## Implicitly restarted Lanczos method

Initial vector  $r_0$

**repeat**

    Compute Lanczos basis  $V_m$  and projection  $T_m$

    Compute spectrum of  $T_m$

    Choose shifts  $\theta_{j_1}, \dots, \theta_{j_p}$

$Q = I_m$

**for**  $i := 1, \dots, p$  **do**

        QR-factorize:  $Q_i R_i = T_m - \theta_{j_i} I$

$T_m := Q_i^T T_m Q_i$

$Q := Q Q_i$

**end for**

$r_k = t_{k+1,k} v_{k+1} + q_{mk} r_m$

    Truncate  $T_m \rightarrow T_k \in \mathbb{R}^{k \times k}$  and  $Q \rightarrow Q \in \mathbb{R}^{m \times k}$

$V_k = V_m Q$

**until**  $T_k$  almost diagonal

# Locking and implicit restart

- ① Begin locking Ritz values  $\theta$  whenever the residual is small
- ② After  $k$  values have been locked and a new one converges
  - ① If is more desirable than one of the previous
    - lock it and
    - release the least desirable locked one
  - ② If it is not more desirable than any, replace  $v_{k+1}$  by a random initial vector and start from there
- ③ End if the random restart failed twice

randomized SVD ?

## Implicitly restarted Arnoldi method

The same method for non-Hermitian EVP, yielding a projected matrix not in tridiagonal, but in Hessenberg form.

- 1 Vector iterations
- 2 Krylov space methods
- 3 The Jacobi-Davidson Method**

## Jacobi-Davidson for a single eigenvalue

Initial vector  $w$

$$v_0 = \frac{1}{\|w\|} w$$

**for**  $m := 1, \dots$  **do**

$v_m = \frac{1}{\|w\|} w$

$T = V_m^T A V_m$

Compute largest eigenpair  $(\theta, s)$  of  $T$

$u = V_m s$

$r = Au - \theta u$

**if**  $\|r\| < \varepsilon$  **then stop**

Solve approximately  $P_u^\perp (A - \theta I) P_u^\perp w = -r$

Orthogonalize  $w$  with respect to  $V_m$

**end for**

# The projected system

- The Galerkin projection of  $A$  can be built recursively adding one row and column

$$T_m = V_m^T A V_m \left( \begin{array}{c|c} T_{m-1} & v_m^T A v_{m-1} \\ \hline v_{m-1}^T A v_m & v_m^T A v_m \end{array} \right)$$

- Since the vectors  $v_j$  are not obtained by short recursion, the matrix is full
- Full QR method needed

# The new search direction

- Search orthogonal to the current Ritz vector  $u$ :

$$P_u^\perp = (I - uu^T)$$

- Solves the problem

$$(I - uu^T)(A - \theta I)(I - uu^T)w = -r$$

$$(A - \theta I)w = -r$$

on the subspace orthogonal to  $u$ .

- $\|u\| = 1$  and the eigenvector has length one
  - Search tangential to the unit sphere
- Exact solution not necessary, since projected matrix is computed explicitly
  - Can be replaced by any other operator

# Another view to the Davidson method

- The shift  $\theta$  for inversion is adapted in each step
  - Projection version of the Rayleigh quotient iteration
- The matrix  $A - \theta I$  becomes more and more singular as  $\theta$  improves
  - Condition number grows
  - The projection improves the condition number

## Jacobi-Davidson for several eigenvalues

Initial vector  $w$

$$v_0 = \frac{1}{\|w\|} w$$

**for**  $m := 1, \dots$  **do**

$$v_m = \frac{1}{\|w\|} w$$

$$T = V_m^T A V_m$$

Compute largest eigenpairs  $(\theta_k, s_k)$  of  $T$

$$u_k = V_m s_k, \quad k = 1, \dots, \ell$$

$$r_k = A u_k - \theta_k u_k, \quad k = 1, \dots, \ell$$

**if**  $\|R\| < \varepsilon$  **then stop**

Solve approximately  $P_U^\perp (A - \theta I) P_U^\perp w = -r$

Orthogonalize  $w$  with respect to  $V_m$

**end for**

- The Ritz vectors form an orthogonal matrix

$$U = (u_1, \dots, u_\ell) \in \mathbb{R}^{n \times \ell}$$

- The new orthogonal projection is

$$P_U^\perp = (I - UU^T)$$

- $\theta$  is still chosen as the largest Ritz value

# Further improvements

- Locking of converged eigenvalues
- Implicit restart

- Vector iterations
  - Amplify desired eigenvectors by applying matrix powers
- Projection methods
  - Accelerate by solving projected problems exactly
  - Projected problems are of dimension greater one
  - Lanczos accelerating power and inverse iteration
  - Davidson accelerating Rayleigh quotient iteration